



Contactless Apprehension of Traffic Violators on 24-hours Basis All-Vehicle Detection System (CATCH-ALL)

FUNDED BY

Department of Science and Technology – Philippine Council for Incustry, Energy, and Emerging Technologies for Research and Development (DOST-PCIEERD)

PROJECT PROPONENTS

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Objective Attainments

OBJECTIVES	DESIGN: SOFTWARE/ HARDWARE	IMPLEMENTATION
1. To implement a machine vision system that will capture vehicle images on the street intersection in real time.	100% Complete	75% Complete
2. To design and develop an Artificial Intelligence (AI) software that can do the following:	100% Complete	75% Complete
a) identify the vehicle plate using a camera vision,	100% Complete	75% Complete
b) identify number coding and reckless driving (swerving) traffic violations and provide immediate notification to the violators, and	100% Complete	75% Complete
c) provides unquestionable evidence on the traffic violations committed.	100% Complete	75% Complete
3. To integrate the results of objectives 1 to 2 and implement the Automated Traffic Violation Detection and No-contact Apprehension System (CATCH-ALL) on the traffic intersection of Taft-Estrada street, Malate, Manila in real time	80% Complete	50% Complete

Objective Attainments

OBJECTIVES	DESIGN: SOFTWARE/ HARDWARE	IMPLEMENTATION
4. To conduct actual study on the effects of CATCH-ALL in the street traffic.	-	20% Complete
5. To conduct actual study on the Filipino drivers' behavior towards the implementation of CATCH-ALL.	-	10% Complete

- 1. PUBLICATIONS
- 2. PRODUCTS OR PROCESS
- 3. PATENTS
- 4. PEOPLE SERVICES / CAPABILITY BUILDING
- 5. PLACES AND PARTNERSHIPS
- 6. POLICY

PUBLICATIONS

List of papers published in IEEE HNICEM 2015 in Cebu, Philippines:

- 1. A genetic algorithm and artificial neural network-based approach for the machine vision of plate segmentation and character recognition
- 2. Machine vision for traffic violation detection system through genetic algorithm

List of papers published in *IEEE TENCON 2016* in Singapore:

- Automated Traffic Violation Apprehension System Using Genetic Algorithm and Neural Network
- 2. Fuzzy Logic Based Vehicular Plate Character Recognition System Using Image Segmentation and Scale-Invariant Feature Transform
- 3. Intelligent System Architecture for a Vision-Based Contactless Apprehension of Traffic Violations
- 4. Machine Vision of Traffic State Estimation Using Fuzzy Logic
- 5. Passenger Demand Forecast Using Optical Flow Passenger Counting System for Bus Dispatch Scheduling
- 6. Philippine Vehicle Plate Localization using Image Thresholding and Genetic Algorithm

PUBLICATIONS

List of papers to be published in Science and Information (SAI) Computing Conference 2017 in London, UK:

 Vehicle Detection and Tracking Using Corner Feature Points and Artificial Neural Networks for a Vision-based Contactless Apprehension System

List of papers to be published in JACIII (Journal of Advanced Computational Intelligence and Intelligent Informatics):

Traffic Estimation and Warning System using Fuzzy Logic and GSM

PRODUCTS OR PROCESS

Software packages: Detecting traffic violations and contactless apprehension notice

- Vehicle detection and tracking
- Plate number localization and recognition
- Vehicle profiling (class and color)
- Number coding violation detection
- Beating the red light detection
- Swerving detection
- Over-speeding detection
- Traffic violation information system

PATENTS

No pending patent application

Possible

- 1. Computer-implemented inventions
- 2. System architecture patents

PEOPLE SERVICES / CAPABILITY BUILDING

List of graduate student/researchers:

NAMES	COURSE	EXPECTED YEAR OF GRADUATION
1. Robert Kerwin Billones	PHD-ECE	3 rd Term 2017-2018
2. Edison Roxas	PHD-ECE	3 rd Term 2018-2019
3. Rhen Anjerome Bedruz	MS-ECE	2 nd Term 2016-2017
4. Ana Riza Quiros	MS-ECE	2 nd Term 2016-2017
5. Aaron Christian Uy	MS-ECE	2 nd Term 2016-2017
6. Noel Alarcon	MS-ECE	2 nd Term 2016-2017
7. Jinmar Valentino	MS-CS	2 nd Term 2016-2017

PLACES / PARTNERSHIPS

- 1. MANILA CITY GOVERNMENT AND AFFECTED BARANGAYS
- 2. MANILA TRAFFIC AND PARKING BUREAU (MTPB)
- 3. METRO MANILA DEVELOPMENT AUTHORITY (MMDA)- Given access to CCTV database
- 4. DEPARTMENT OF TRANSPORTATION (DOTr) possible candidate
- 5. LAND TRANSPORTATION OFFICE (LTO) possible candidate

POLICY

 Coordination with Manila Traffic and Parking Bureau for establishing Traffic Discipline Zone in Taft Ave. to Singalong Ave. along Estrada St.

Other possible policies:

- Implementation in Taft-Estrada, Manila City for driver behavior monitoring (for traffic violations) which can be expanded to other MM roads.
- 2. Traffic Violations No-Contact Apprehension for LTO

POLICY



Establishment of Traffic Discipline Zone

POLICY



Starting Point of Traffic Discipline Zone

YOU ARE ENTERING A
TRAFFIC DISCIPLINE ZONE
OBEY TRAFFIC RULES & REGULATIONS
VIOLATORS WILL BE APPREHENDED

POLICY







Traffic Signage in the Traffic Discipline Zone

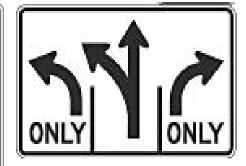
POLICY





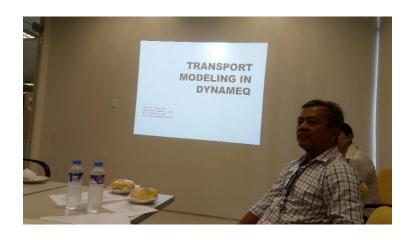


MUST
TURN LEFT

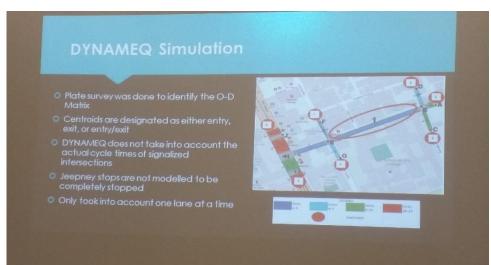


RIGHT LANE
MUST
TURN RIGHT

POLICY



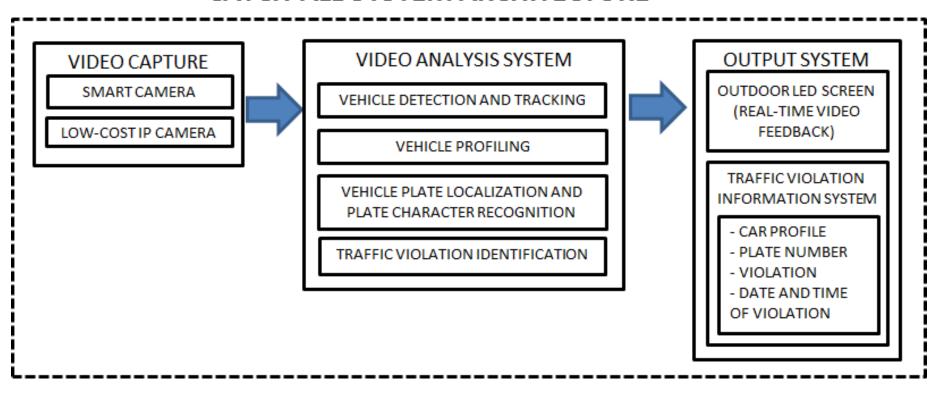
Meeting with MTPB



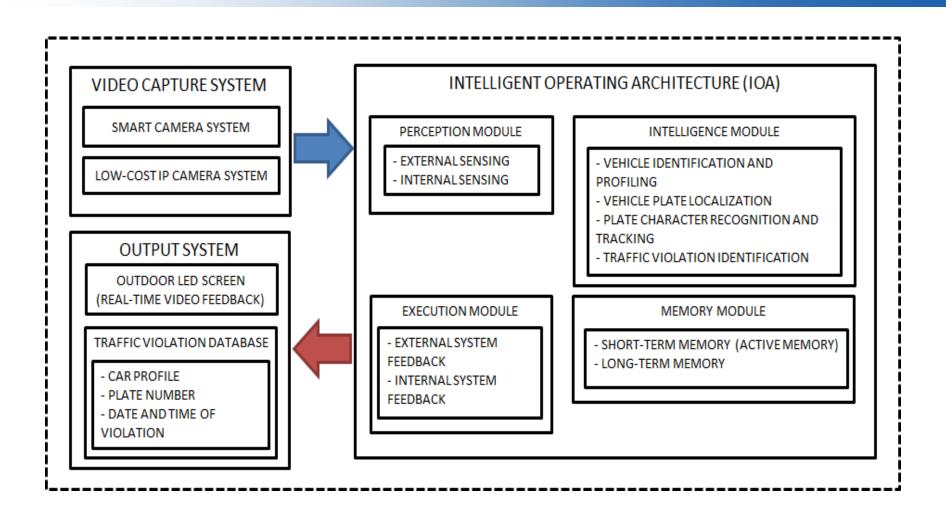


OVERVIEW OF THE PROJECT

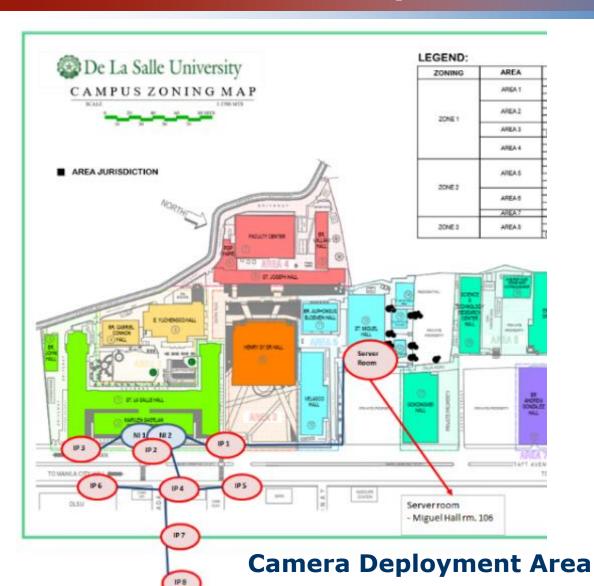
CATCH-ALL SYSTEM ARCHITECTURE



Vision-Based Contactless Apprehension System



Video Capture Sub-System



NI 1778 Smart Camera (1.6GHz Atom Processor, 5MP, Monochrome) 781859-01



NI 1776C Smart Camera (1.6GHz Atom Processor, 2MP, Color) 781858-01





Video Capture Sub-System



Camera Locations and Views







Computing Server



- Tesla computing processor, 256 Cores
- 40 Terabytes of storage data
- Running on Linux (CentOS 7)
- Programming environment ready for use
 - Additional libraries can be installed as needed
 - Automatic connection to the NAS (drives)

Computing Server



- Configured as shared storage (hard drives) for the server and all networkconnected computers
- Also configured as credential server for Windows and Linux
- Information and any recorded videos from the IP cameras will be stored here

Computing Server

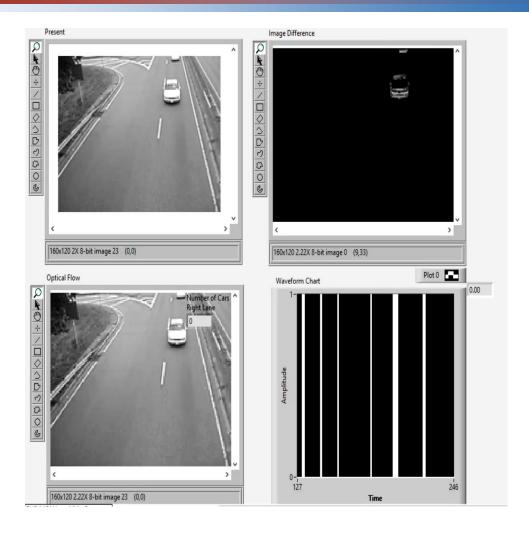


- Two units:
 - Main UPS
 - Extra battery
- To be used in case of power failure

Terminal Systems (Desktops)



- Computers fully assembled and operational
 - One motherboard is defective and awaiting replacement
- Basic software configuration complete
 - 3 Linux computers
 - 4 Windows computers
- ❖ Work-in-progress:
 - Licensing (c/o ITS)
 - LabVIEW (c/o ITS)
 - Microsoft Office (c/o ITS)
 - Create accounts for all users (via NAS)



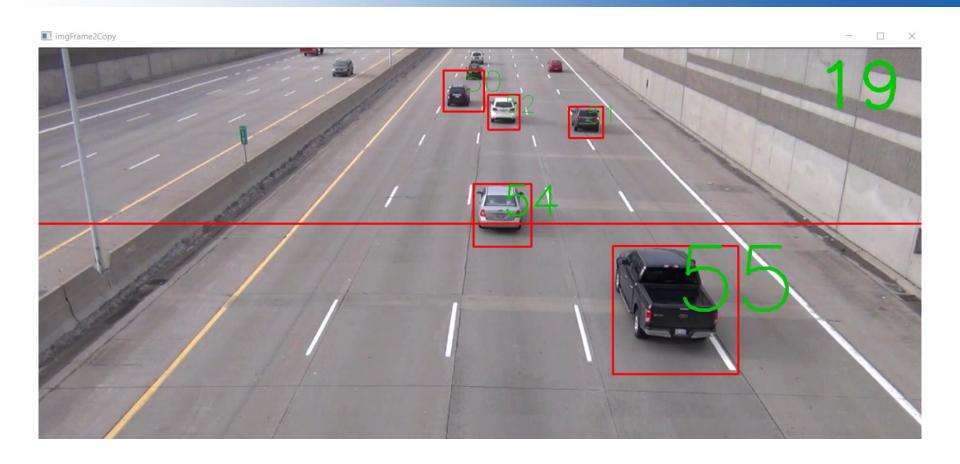
Vehicle Detection and Tracking Experiment 1 (Using Optical Flow in Labview)



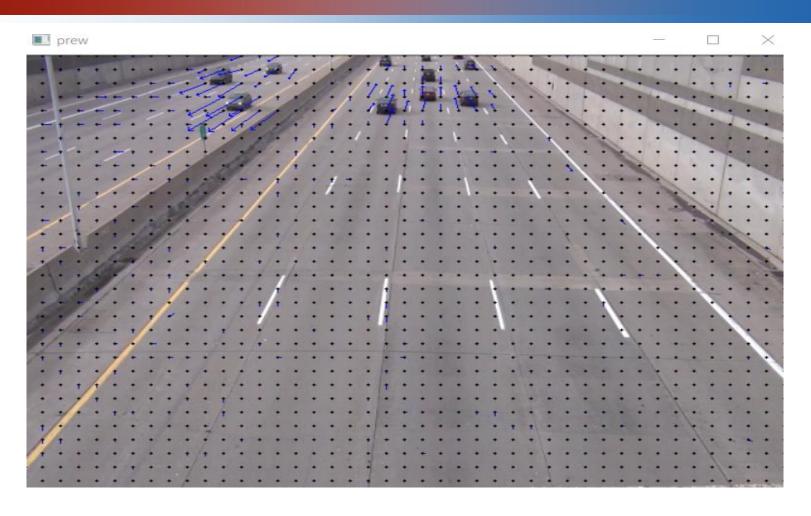
Vehicle Detection and Tracking Experiment 2 (Using Blob Analysis and Kalman Filter in MATLAB)



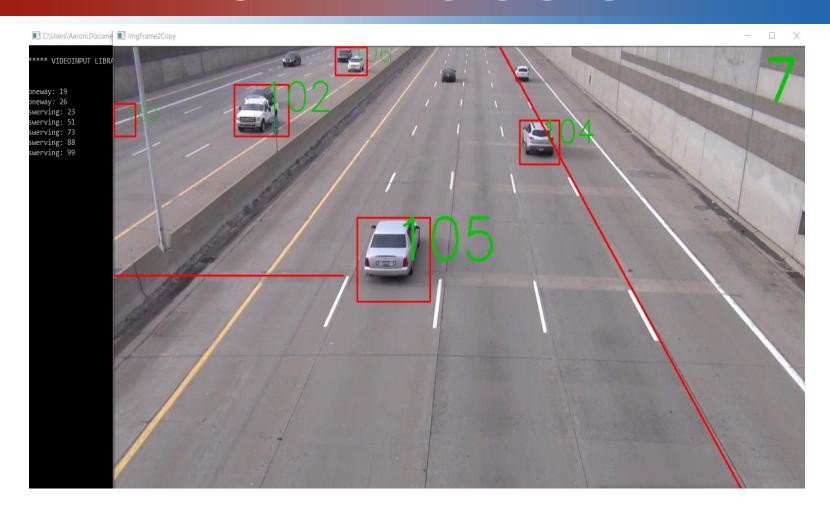
Vehicle Detection and Tracking Experiment 3 (Taft-Estrada Intersection)



Vehicle Detection and Tracking Experiment 4 (Using OpenCV)



Vehicle Detection and Tracking Experiment 5 (Using Optical Flow in OpenCV)



Vehicle Detection and Tracking Experiment 6 (Violation Detection in OpenCV)

Plate Localization System



ORIGINAL IMAGE

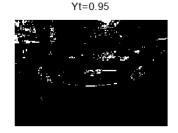


FINAL OBTAINED PLATE LOCATION





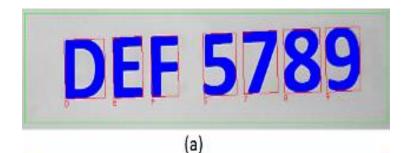


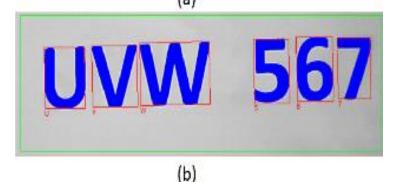


DIGITAL IMAGE AT DIFFERENT THRESHOLDING VALUES



OBTAINED PLATE AREA





Sample Optical Character Recognition

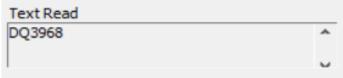














Text Read	
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Text Read	
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OUTPUT SYSTEM

OUTPUT SYSTEM

OUTDOOR LED SCREEN (REAL-TIME VIDEO FEEDBACK)

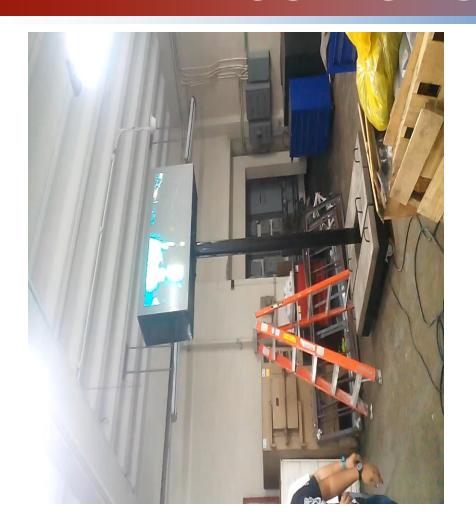
TRAFFIC VIOLATION DATABASE

- CAR PROFILE
- PLATE NUMBER
- DATE AND TIME OF VIOLATION
- TRAFFIC VIOLATIONS
- NUMBER CODING
- BEATING THE RED LIGHT
- SWERVING
- OVERSPEEDING





OUTPUT SYSTEM







Outdoor LED Screen: Hardware and Software Testing

ACTION PLANS

Objectives	Expected Output	Milestone Indicators / Measure	Work Component and/or Tasks	Activities																		
										016				-		-			20			
					Jan	Feb	Mar	Apr	May	Jun	Jul	Au	g Se	p Uc	ct No	v Dec	Jan	Feb	Mar	Apr	May	Jun
to implement the CATCH-ALL Project. 3. To know and acquire all	the CATCH-ALL is installed. 2. Acquisition of needed equipments/materials for CATCH-ALL project. 3. Permit from Manila City LGU for working and installing equipments/materials needed to	statistical analysis of the traffic situation in the area where the CATCH-ALL project is to be implemented. 2. Acquire all CATCH-ALL project equipments/scomponents/material s, available from both local and international market. 3. Appropriate traffic road signage and CCTV camera installations.	Actual experiment and observation on vehicle movement on the target streets. 2 Purchase the equipments which include camera and other materials needed to implement CATCH-ALL projects. 3. Contact and follow up the officials of Mania City LGU regarding the permit to put up thysical improvements in Estrade street corner Taft Avenue. 4. Hire and supervise private contructor to work on road trafficians, camera installations and other civil workd required to implement CATCH-ALL project.	Coular survey of location and assessment for CATCH-ALL implementation. 2 Road side traffic survey before CATCH-ALL implementation. 3. Decision on the actual position of the cameras. 4. Purchase equipment (CCTV cameras and other equipment 5. Bidding for the installation.traffic signs and markings 6. Construction of signage, 7. Installation of basic CCTV cameras and accompanying traffic flow management schemes.								Bi	elayed dding ermits	, Imp	curem	ent, on and						
To design and develop an Artificial Intelligence (Al) software offline that can do the following: a) identify the vehicle plate using a camera vision, b) identify number coding and reckless driving (swerving) traffic violations and provide immediate notification to the violators, and c) provides	A working Program that has the capability to a) identify the vehicle plate using a camera vision, b) identify number coding and reckless driving (swerving) traffic violations and provide immediate notification to the violators, and c) provides unquestionable evidence on the traffic violations	Extract the output of the machine vision system and use it as the input of the Al software. Insure the accuracy, reliability, and robustness of the Al software	development of the AI software. Formulate the development of the AI software. Formulate the concepts of the intelligent algorithms to use. Encode the algorithms into high level programming. Run, test, and debug the program until excellent results are obtained.	Design and develop the CATCH-ALL software using computational intelligence algorithm to identify vehicle plate registration and determine traffic violations and to implement the offline no-contact traffic violator apprehension.								are Te imp	mpute e alrea sting pleme layed leston	ady co on ac entatio due o	omple ctual on is delay	in			Projecte			
on line.	conceitsed The CATCH-ALL working prototype is installed on the field (street intersection). The LED board that will displey information of traffic violators is installed. Recognize, identify vehicle licencse plate and detect, record traffic violators.		Record all the information of the traffic violators in disk storage. Display information of traffic violators on LED board in real time	9. Integrate the developed machine vision system for the vehicle plate recognition on line. 10. Integrate the whole system finally implement the CATCH-ALL on the street intersections in real time. 11. Test and evaluate the performance of the system.											ha	elayed o rdware stallatio						
To conduct actual study on the Filipino drivers' behavior towards the implementation of CATCH- ALL.	Complete study report pertaining to the attitudes of driver's towards the CATCH-ALL.	analysis of the effects of the	Manual experiment and observation on the drivers attitude before and after the CATCH- ALL is installed.	Road side traffic violation count before and after CATCH-ALL implementation. Validation of the number of traffic violators using cameras																		
Submit Completion Report	Produce documents and papers for publication	Acceptance of paper presentation in international conference or journals	Write technical papers	14. Produce final report and a technical paper from the outputs of this research to be published either in an international journal or proceeding of the international conference.																		

ACTION PLANS











- Ongoing Construction of Fiber Optics Cable
- Placement of LED Screen
- Pavement Markings

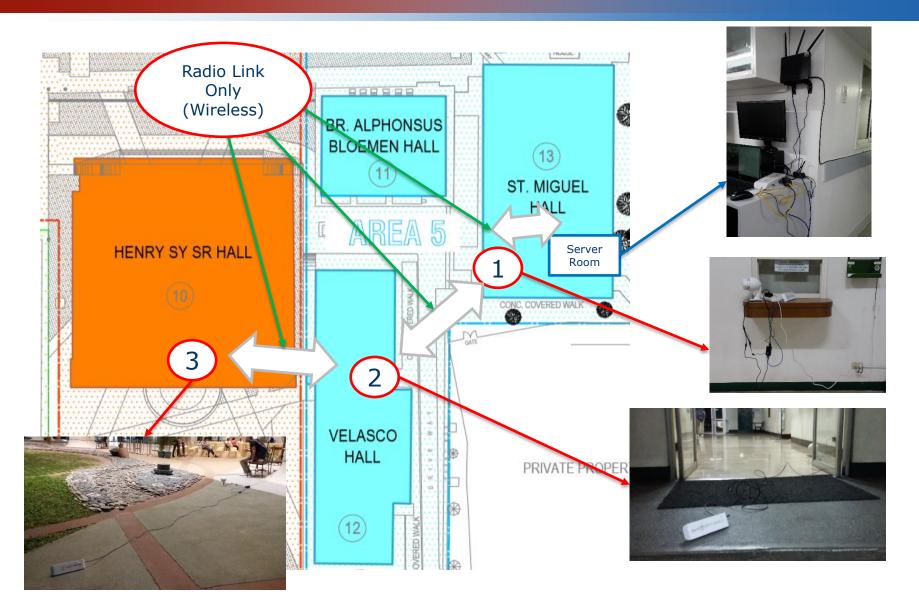


1. <u>WIRELESS MESH COMMUNICATIONS NETWORK FOR VIDEO STREAMING</u>

NOTE:

Video-based networks can be efficiently scaled using a wireless communications network setup. Traditional wired networks are more difficult to scale because of cost and time-delays in construction.

Wireless Video Streaming Experiment Setup



Video Streams from Remote Locations



2. <u>IN-VEHICLE TRAFFIC VIOLATIONS DETECTION FOR PUBLIC UTILITY VEHICLES (BUSES OR TAXIS OR JEEPNEYS)</u>

Computer Vision-Based In-Vehicle Traffic Violations Detection

- Not wearing seatbelt
- Texting while driving

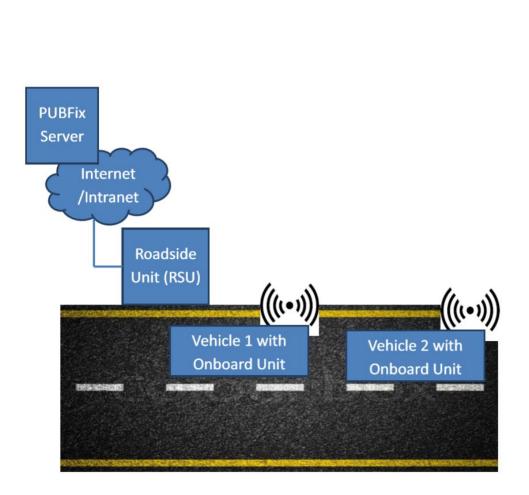
Sensor-Based In-Vehicle Traffic Violations Detection

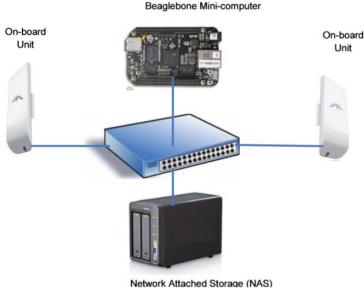
Drunk Driving

NOTE:

Traffic violations will be transmitted to the server whenever the vehicle passes through the road-side unit (RSU)

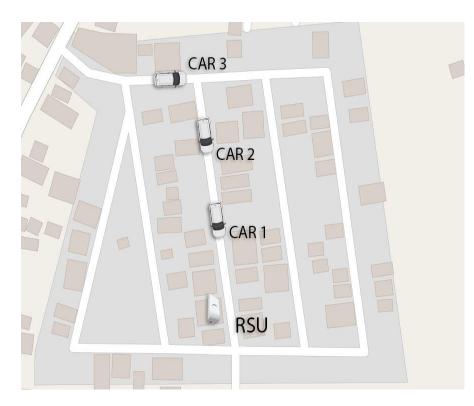
This is an automatic traffic violations detection system and also an accident prevention system.





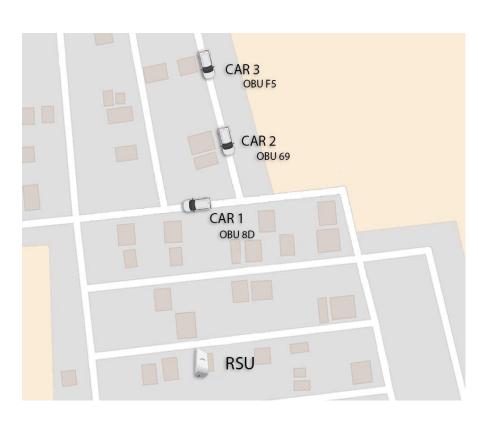
Vehicle Equipment Setup





Gabriela Hills: short distances, narrow roads, more obstructions





Vista Verde: long distances, narrow roads, less obstructions

Test Setup (Typical, 3-Hop Connection)









3. <u>DEVELOPMENT OF TRAFFIC VIOLATIONS INFORMATION SYSTEM AND TRAFFIC VIOLATIONS DATA ANALYTICS USING CATCH-ALL SYSTEM</u>

- Traffic violations information system that runs on web platform will be available to online users. Traffic violations data from no-contact apprehension systems (CATCH-ALL) will be used.
- Traffic violations data analytics from no-contact apprehension systems (CATCH-ALL) are used to analyze traffic patterns in specific routes. These data analytics can be used as guide in decision making by policy makers, traffic law enforcement agencies, and other stakeholders.

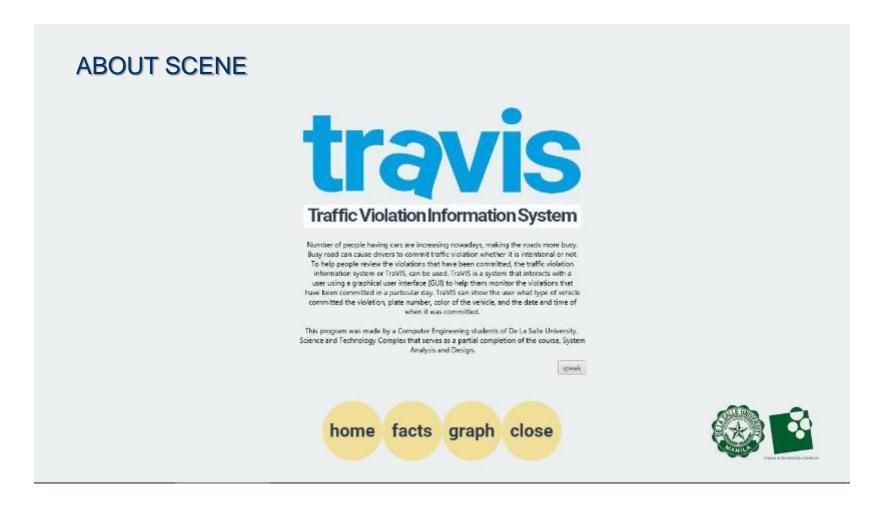
List of violators on the specified traffic violation

VIOLATION	PLATE NUMBER	VEHICLE CLASS	VEHICLE COLOR	DATE VIOLATED	TIME VIOLATE		
PEEDING	abc123	van	blue	January 1, 2016	415		
PEEDING	def456	sedan	red	January 2, 2016	530		
PEEDING	xyz	truck	black	July 3, 2016	300		
DRIVING WITHOUT LICE	хуг	truck	black	November 3, 2016	700		
DRIVING WITHOUT LICE	def456	sedan	red	July 2, 2016	200		
SWERVING	хуг	truck	black	November 3, 2016	500		
WERVING	def456	sedan	red	July 2, 2016	400		
DRUNK DRIVING	def456	sedan	red	January 10, 2016	1100		
COUNTERFLOWING	xyz	truck	black	September 3, 2016	300		

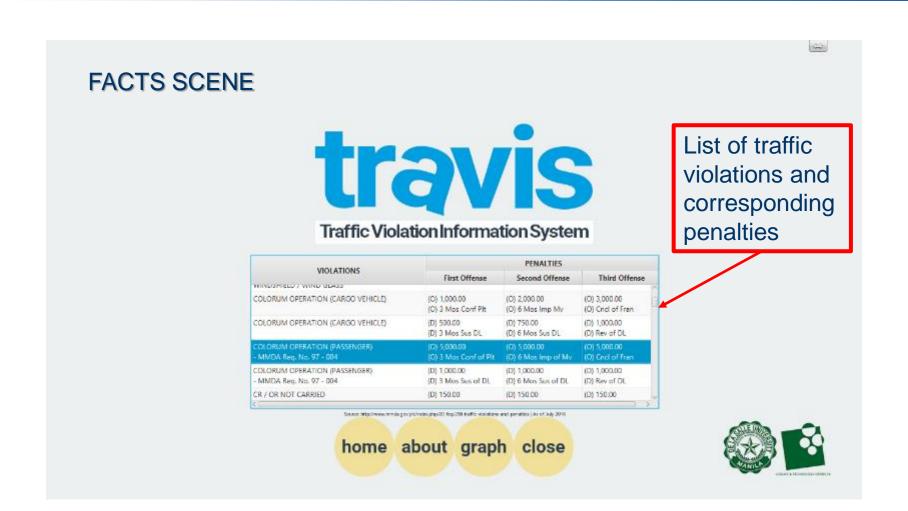
Traffic Violation Information System

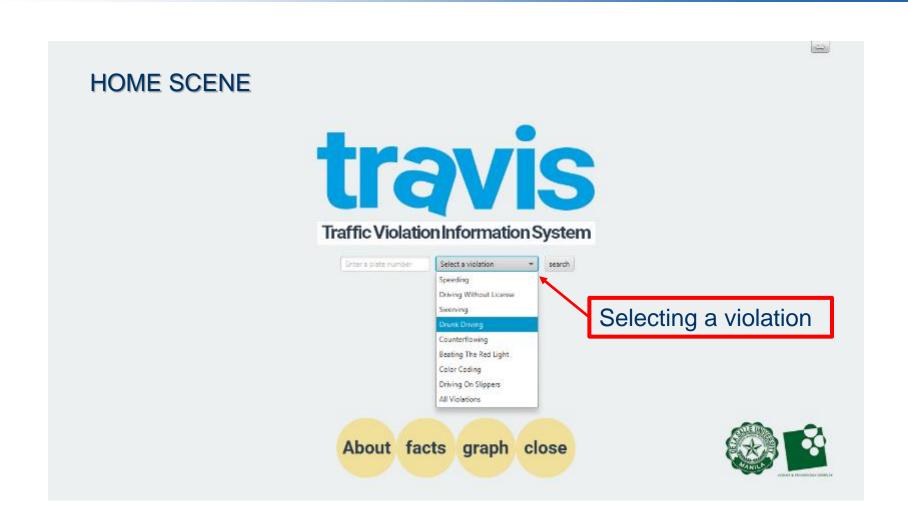
Shows the distribution of violations in daily, weekly, and monthly basis.

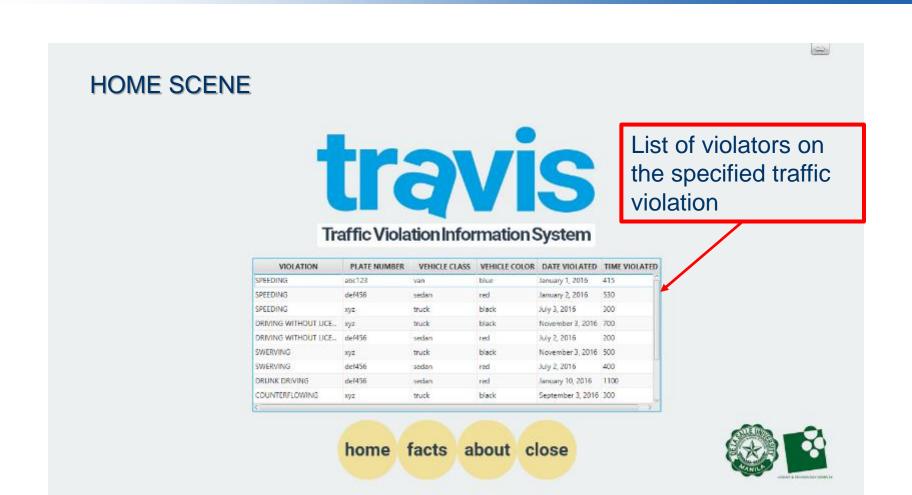




TRAVIS Version 1.0 Development (Traffic Violation Information System)







4. <u>IN-VEHICLE DRIVER BEHAVIOR ANALYSIS AND DRIVER ASSISTIVE TECHNOLOGIES</u>

Computer Vision-Based Driver Assistive Technologies

- Drowsiness detection and speech-based feedback system (driver will be notified/alerted by the computer if he is sleepy)
- Road signs notification and speech-based feedback system (the system will detect road signs and advise the driver to follow traffic rules), ie.
 - Red light notification
 - No loading/unloading notification
 - One-way notification
 - No U-turn notification, etc.

NOTE:

The system can help the drivers in avoiding traffic violations and accidents.

Traffic violations can be recorded if the driver violated the road signs notification. Traffic violations will be transmitted to the server whenever the vehicle passes through the road-side unit (RSU)

5. PUBLIC UTILITY VEHICLES (BUS, TRAINS, ETC.) ON-BOARD SECURITY SYSTEM USING AUDIO-VISUAL MULTIMEDIA SYSTEM

Computer Vision- and Audio-Based Security System for Detecting People's Behavior and Activity in Public Utility Buses

- Detection of deadly weapons (guns, knives, etc.)
- Audio-visual commotion detection during robbery/hold-up, hostage taking, and bomb threats
- Monitoring road conditions (illegal parking, accidents, etc.)

NOTE:

Activity will be transmitted to the server whenever the vehicle passes through the road-side unit (RSU)

6. <u>AUTOMATED PARKING SPACE DETECTION SYSTEM USING COMPUTER VISION AND SMARTPHONE APPS</u>

 Computer vision are used to detect vehicles entering and leaving a parking area. Smartphone app users are notified in real-time of possible parking space in nearby locations.

NOTE:

The system aims to minimize traffic congestions due to vehicle owners unable to find a parking space. It can also minimize illegal parking violations.

